

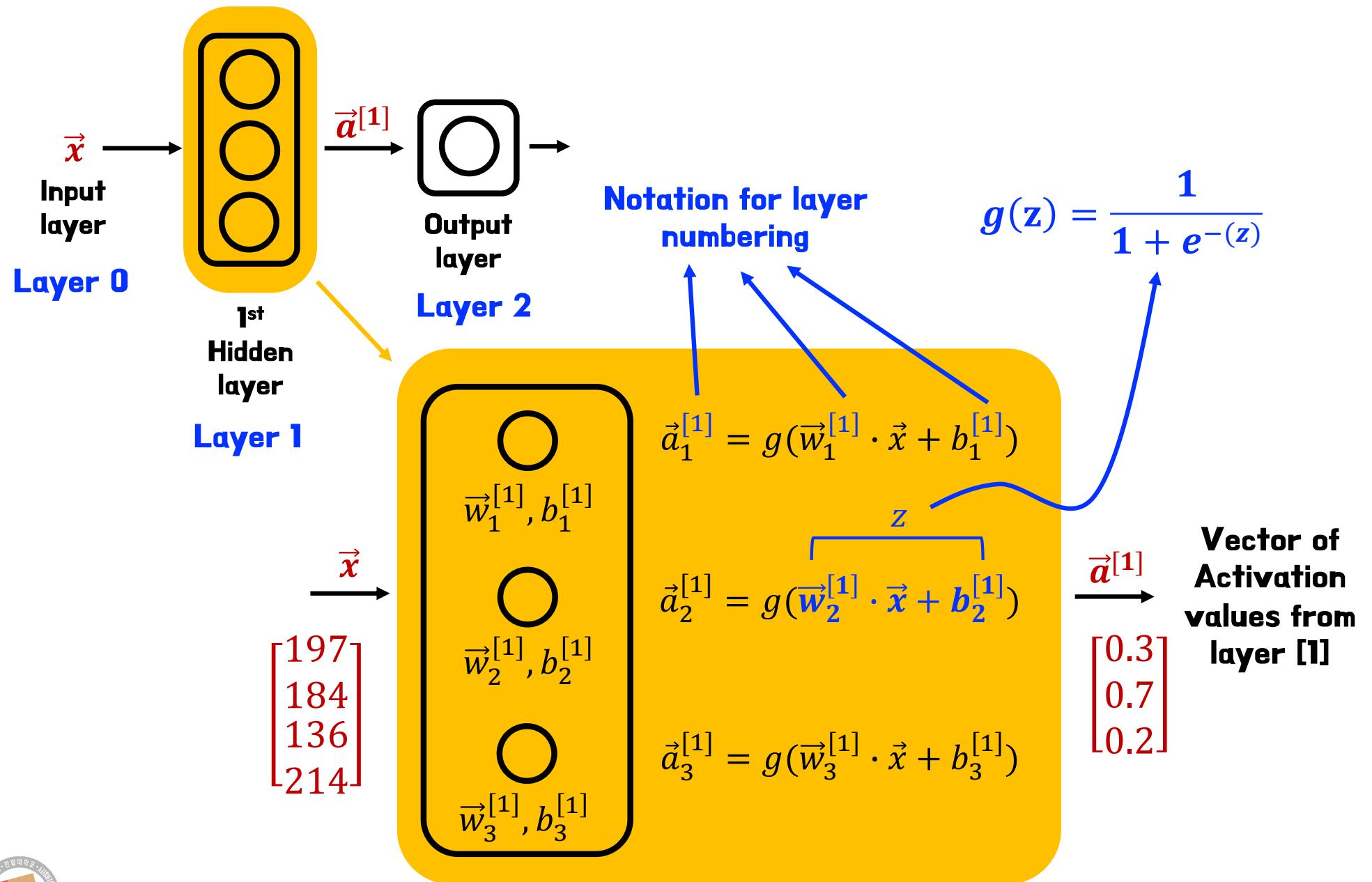
# Machine Learning 06

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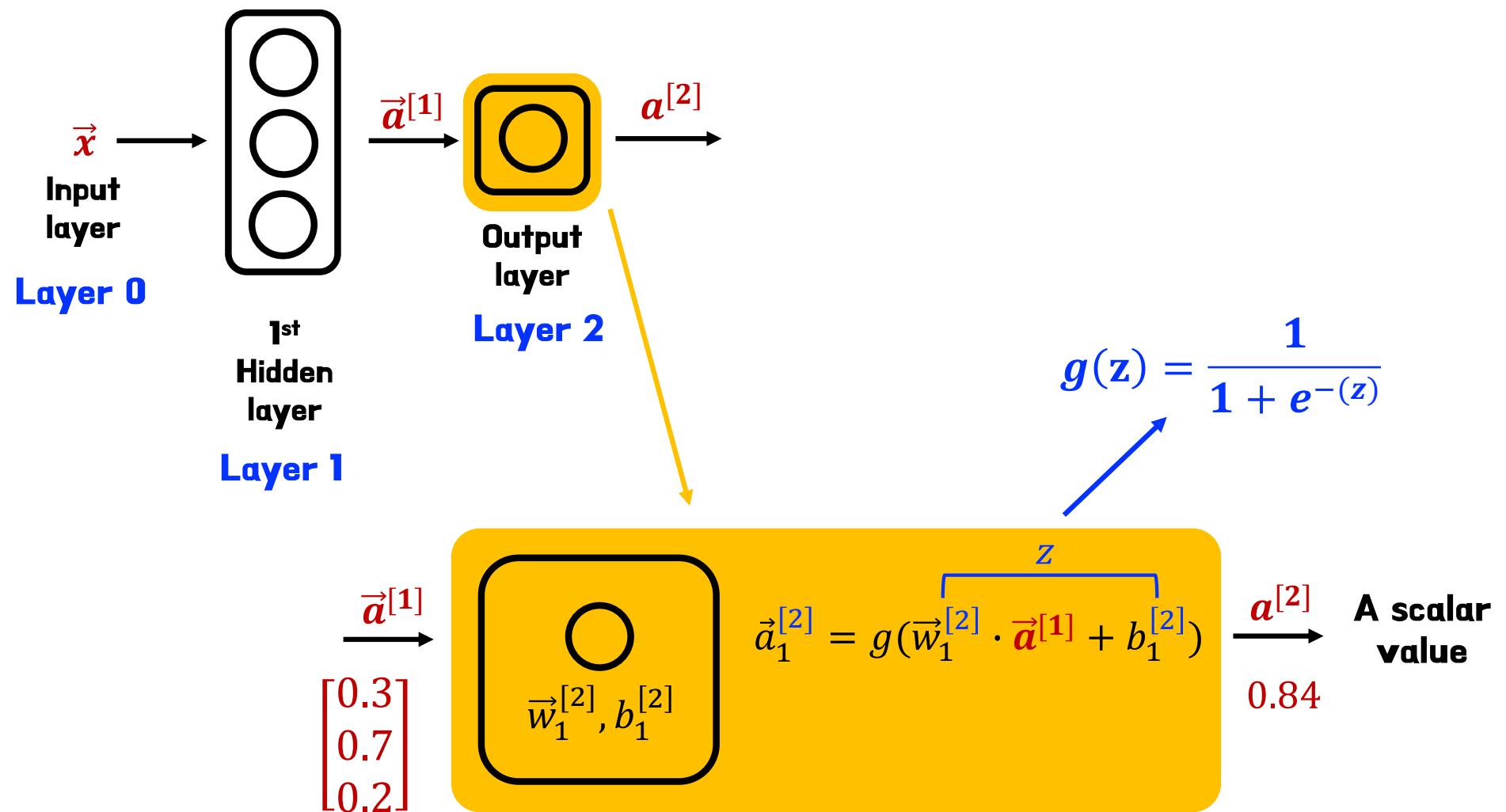
# **Neural network layer**



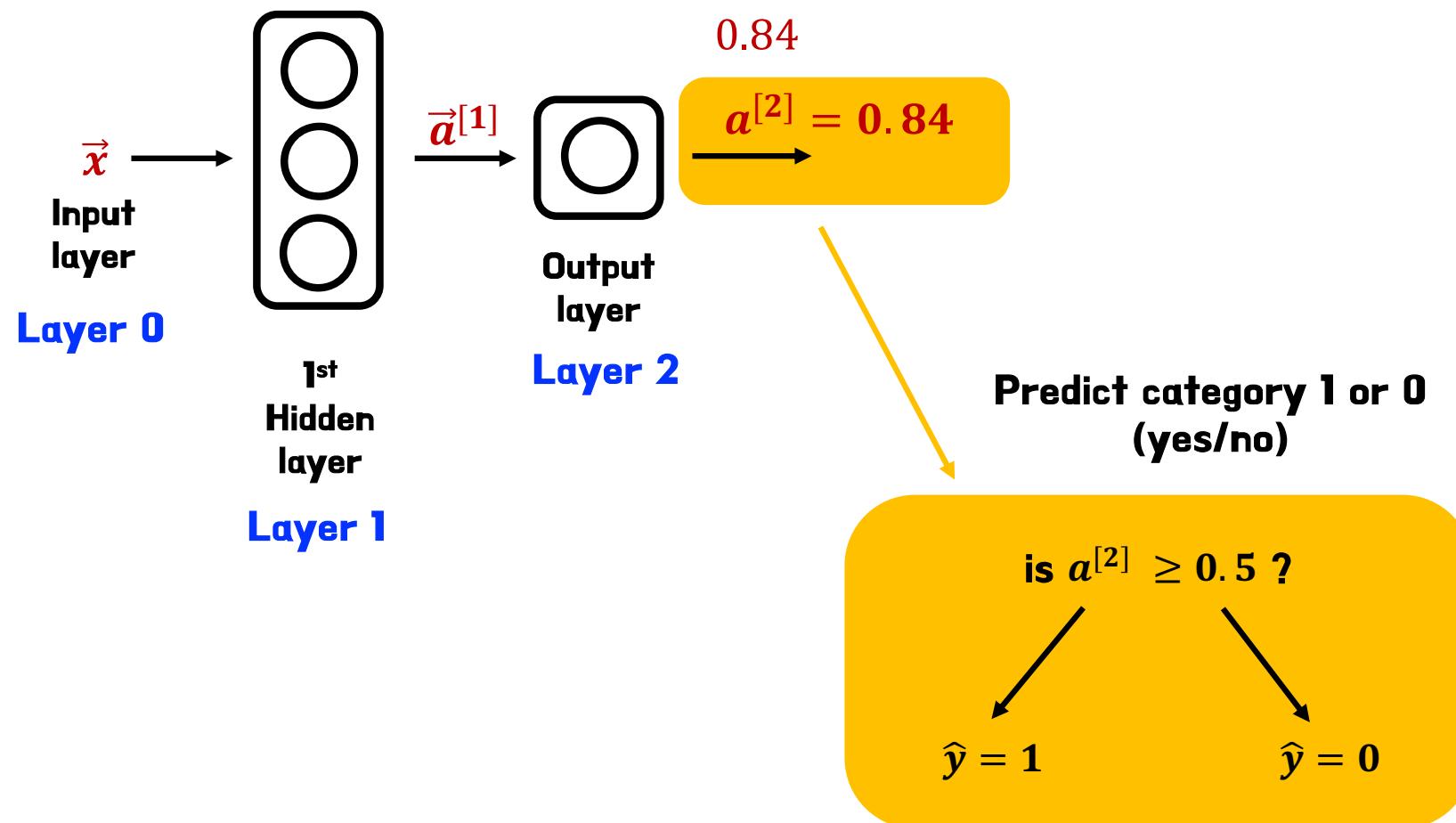
# Neural network layer



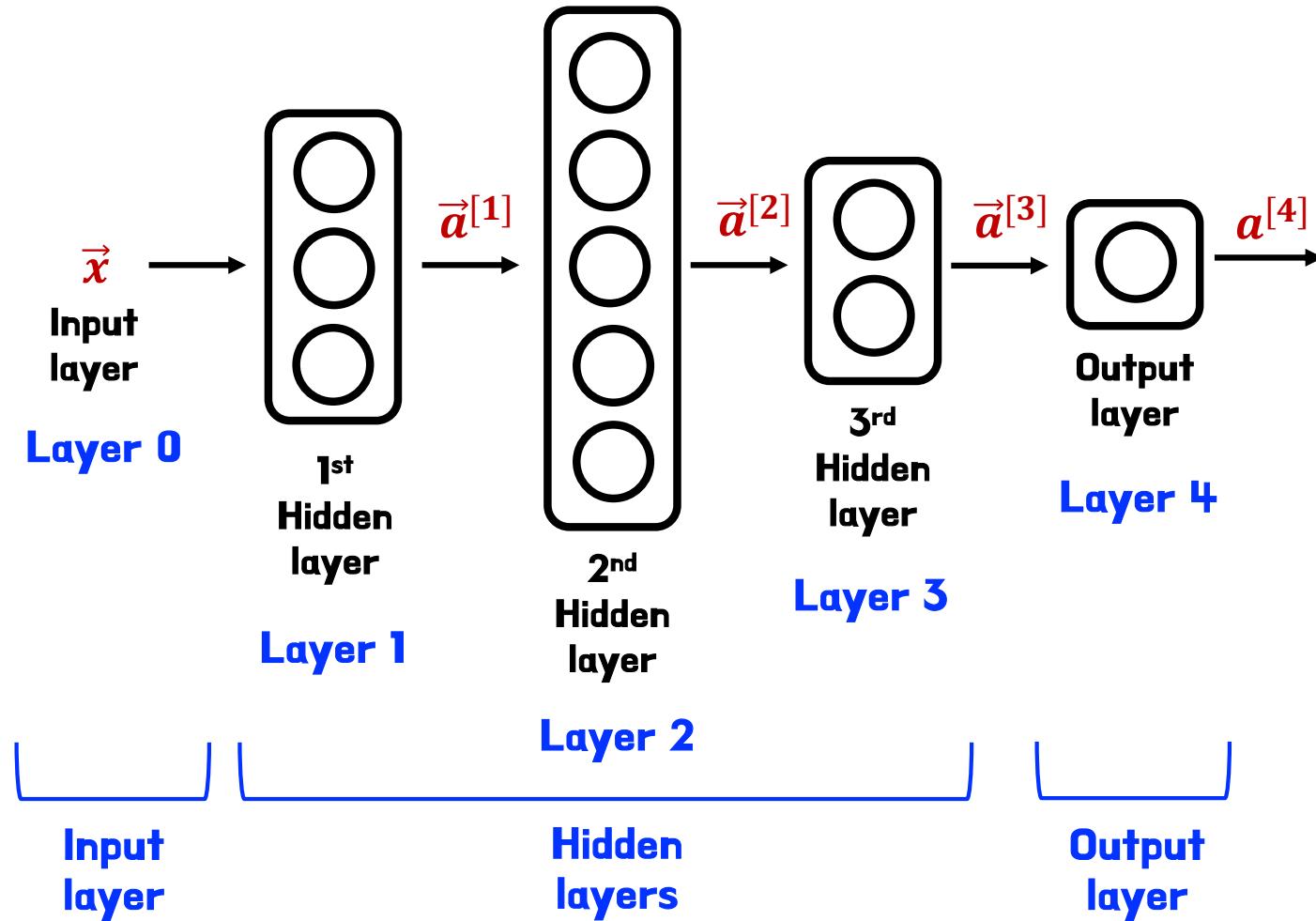
# Neural network layer



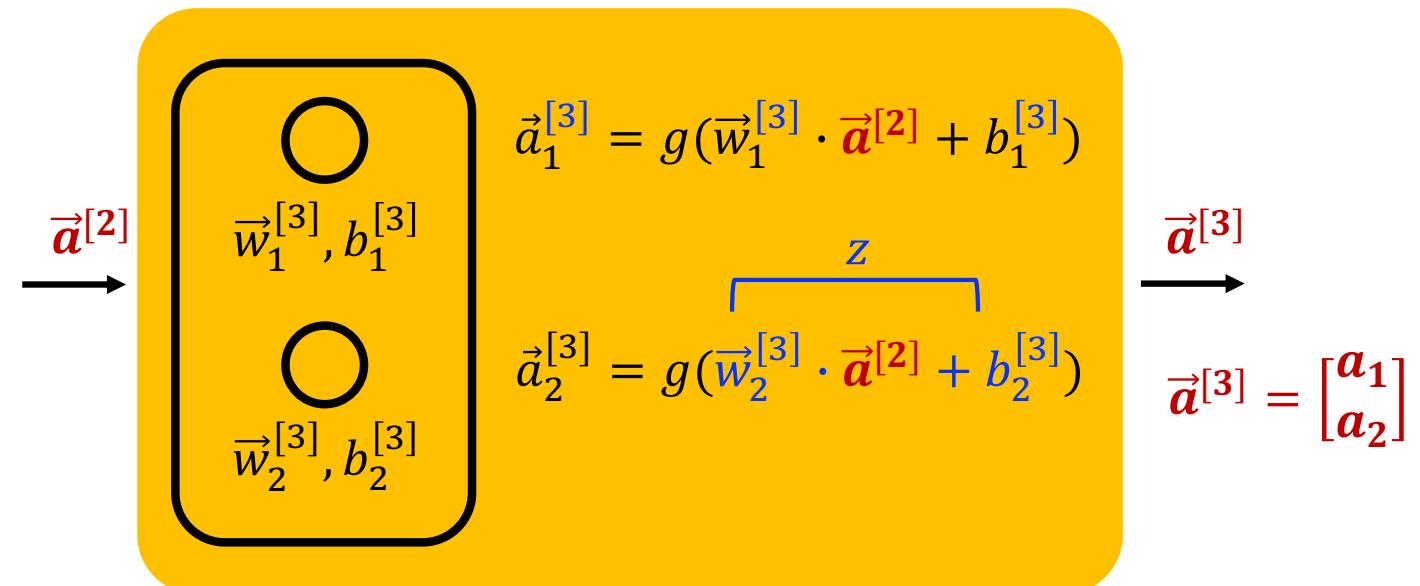
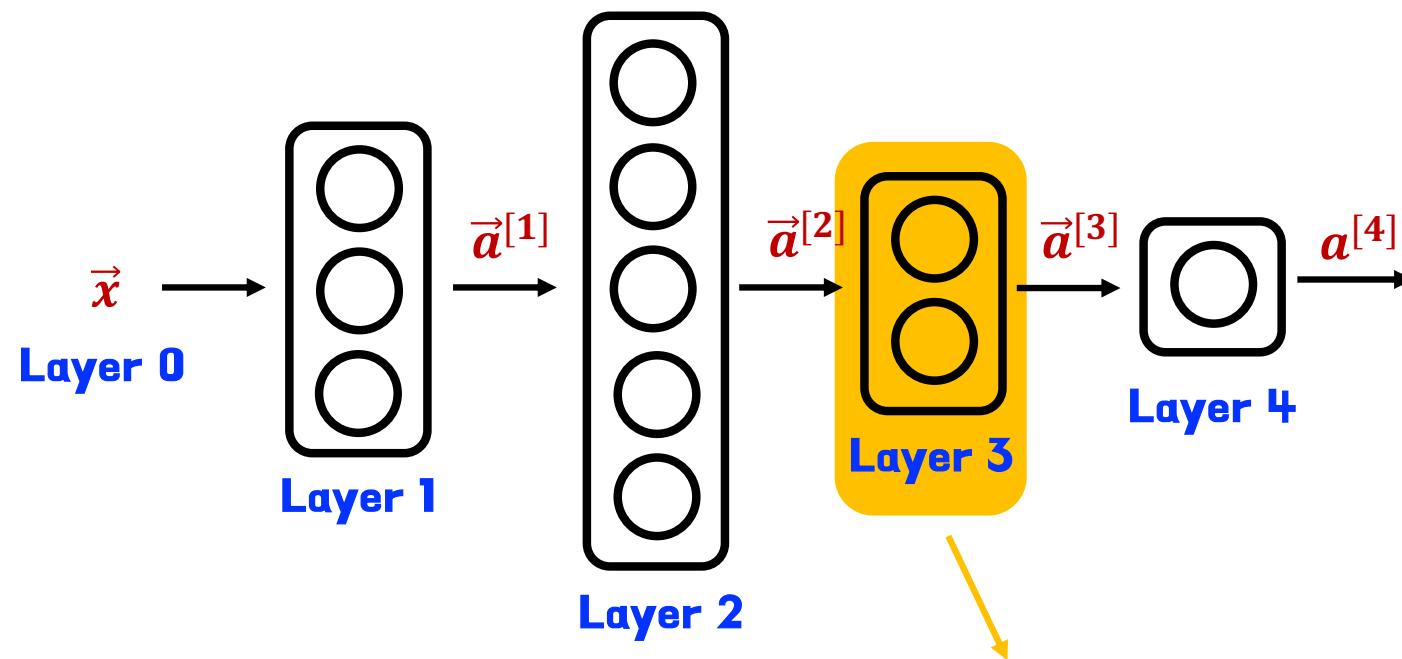
# Neural network layer



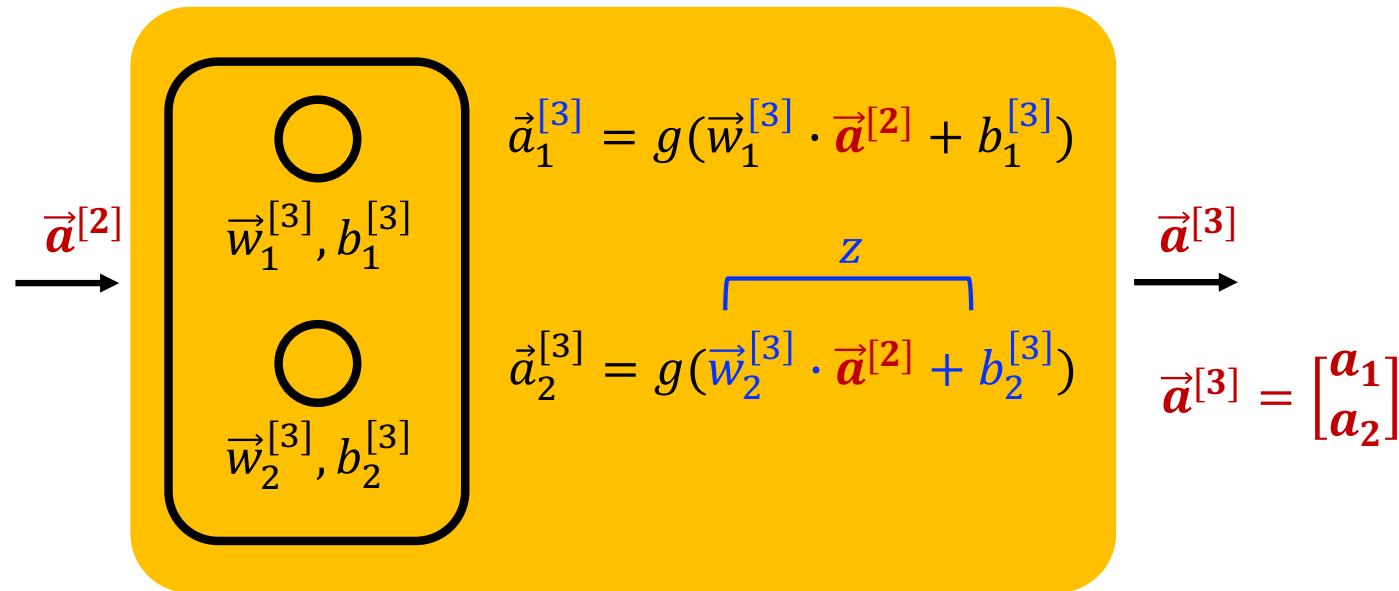
# More complex neural network



# More complex neural network



# More complex neural network



Activation value of  
layer  $l$ , unit (neuron)  $j$

Output of layer  $l - 1$   
(previous layer)

$$\vec{a}_j^{[l]} = g(\vec{w}_j^{[l]} \cdot \vec{a}^{[l-1]} + b_j^{[l]})$$

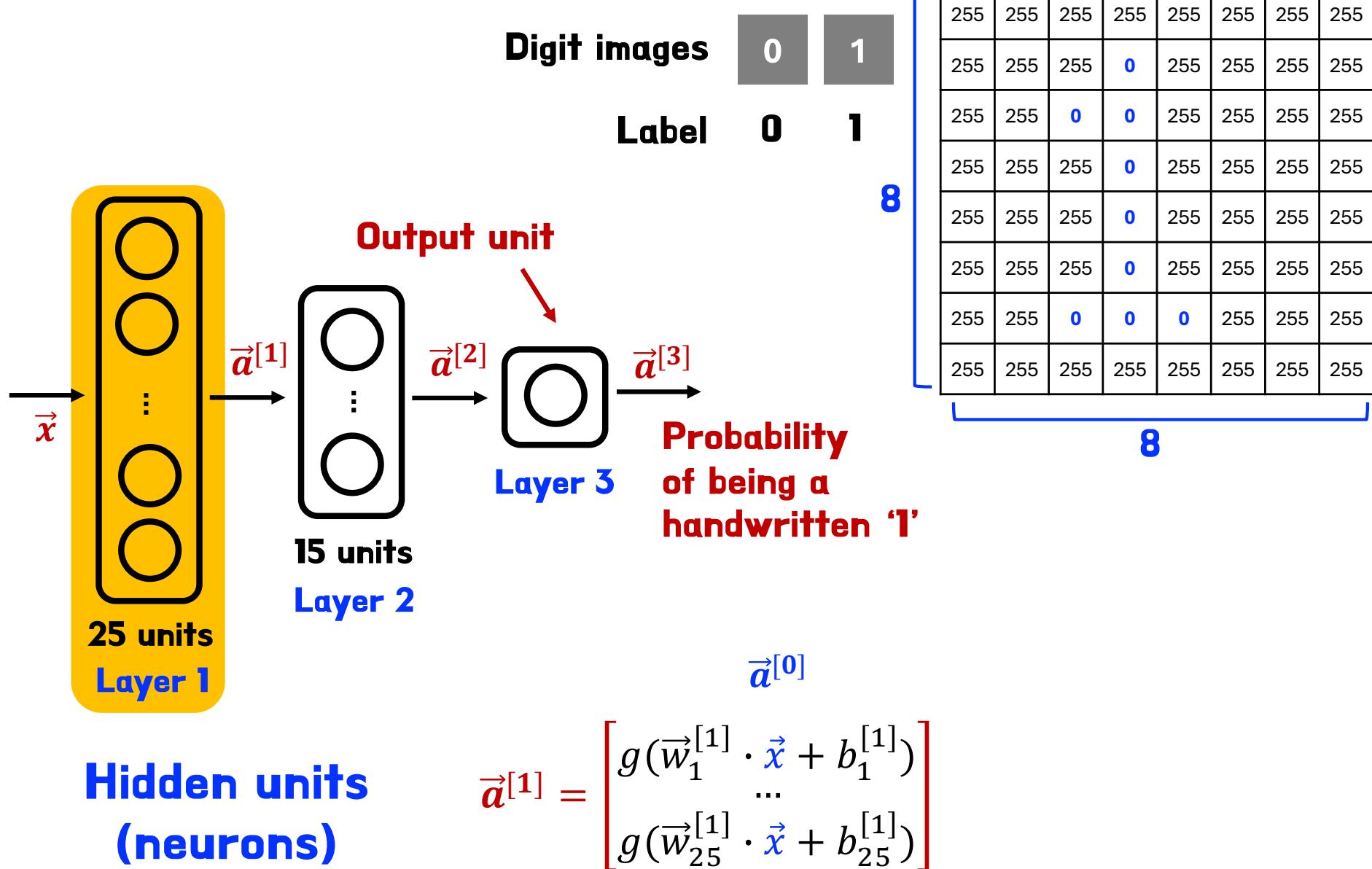
Sigmoid  
“activation function”

Parameters  $w$  &  $b$  of  
layer  $l$ , unit  $j$

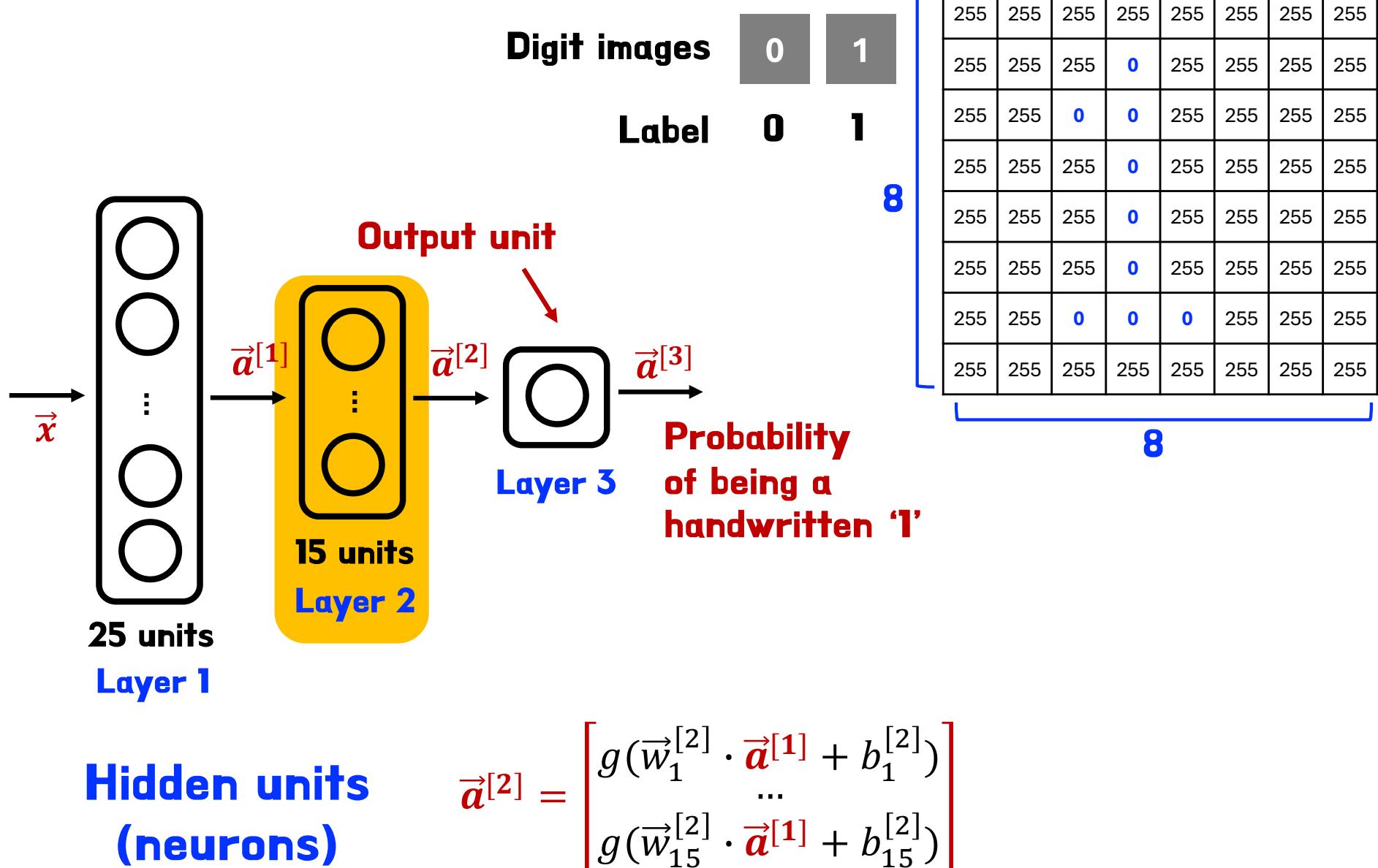
# **Inference: making predictions (forward propagation)**



# Handwritten digit recognition

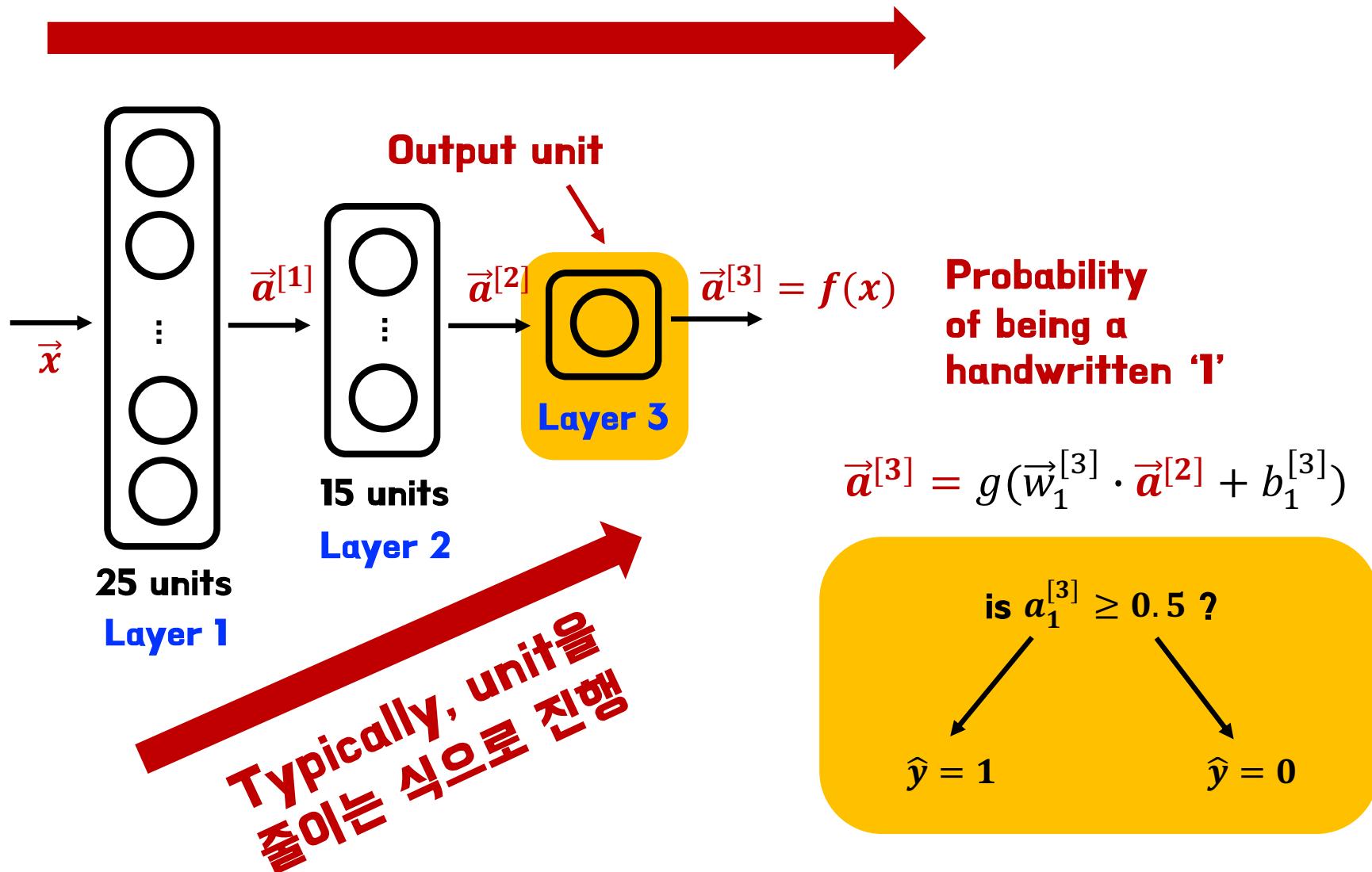


# Handwritten digit recognition



# Handwritten digit recognition

## Forward propagation



# **Speculation on artificial general intelligence (AGI)**



# AI

## ANI

(artificial  
narrow  
intelligence)

e.g.) smart speaker,  
self-driving car, web  
search, AI in farming  
and factories

## AGI

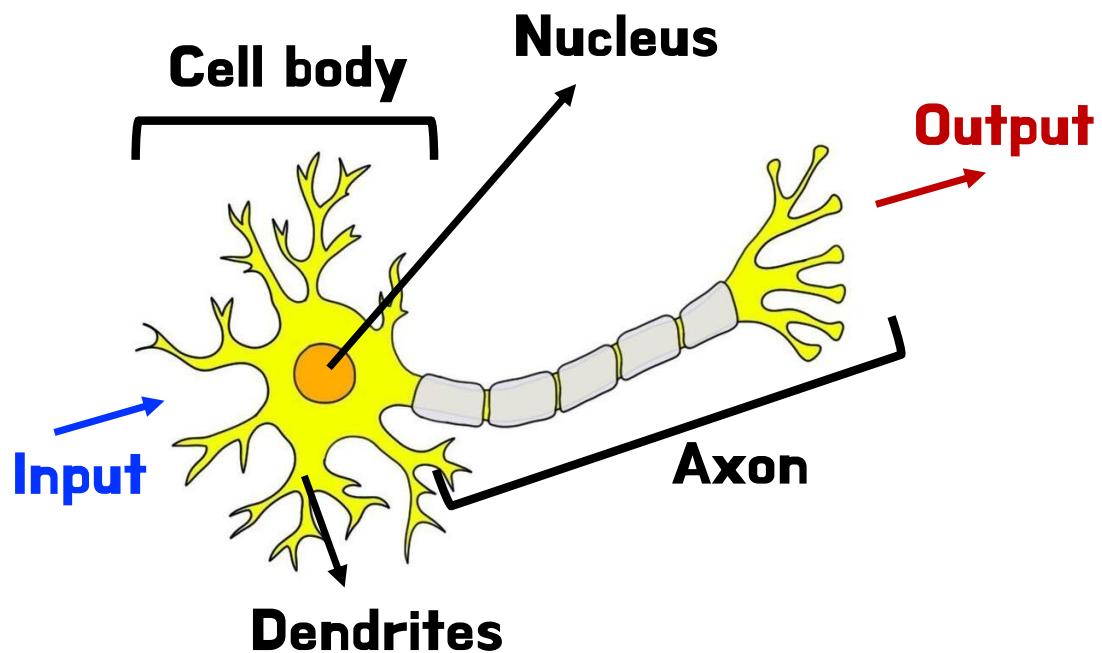
(artificial  
narrow  
intelligence)

Do anything a  
human can do

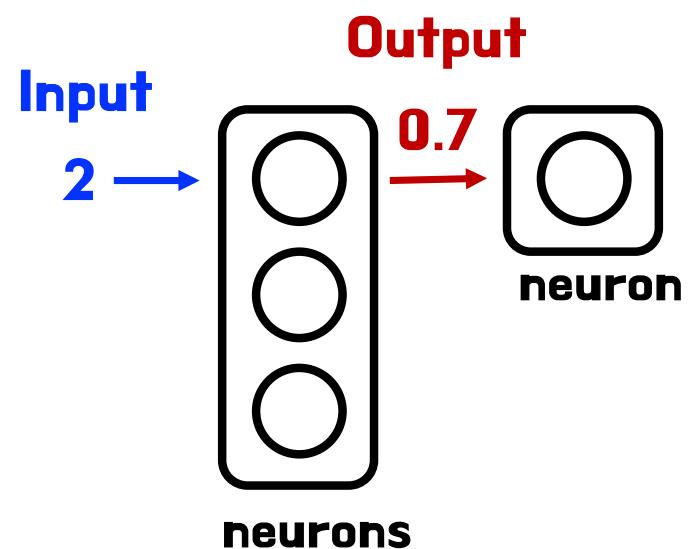


# Neural network and the brain

## Biological neuron



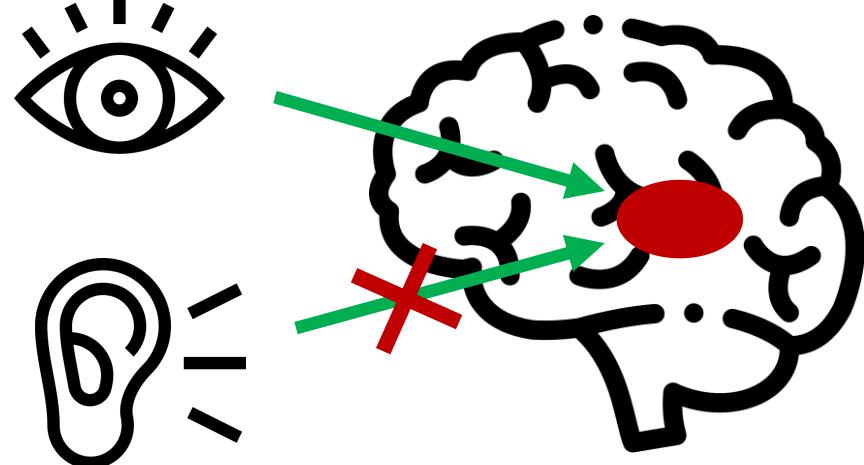
## Simplified mathematical model of a neuron



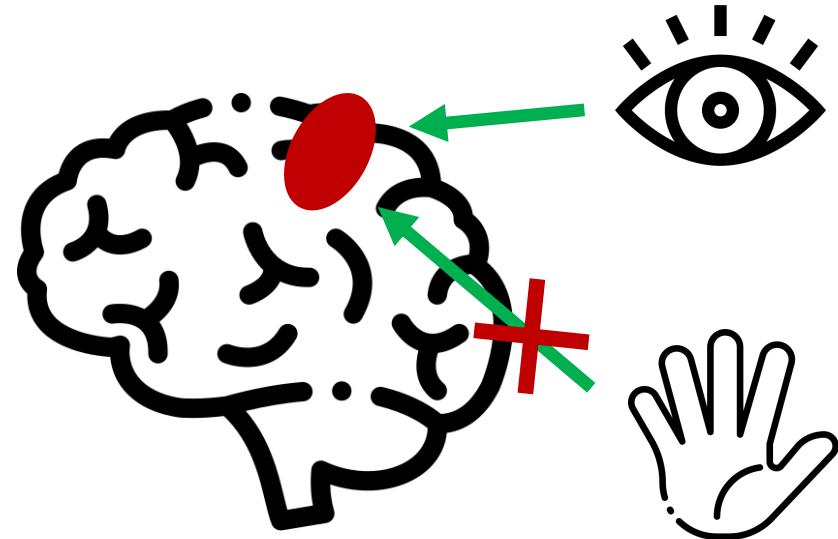
Can we mimic the human brain ?

1. Machine learning is too simple
2. We don't know how the brain works

# The “one learning algorithm” hypothesis



**Auditory cortex**



**Somatosensory cortex**

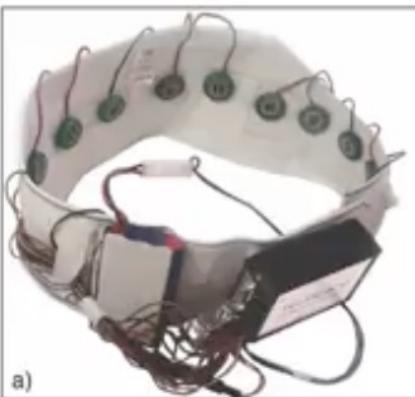
**One brain cortex can learn other sense as well**

# Sensor representations in the brain

We don't know if it is possible in machine learning



Seeing with your tongue



Haptic belt: Direction sense



Human echolocation (sonar)

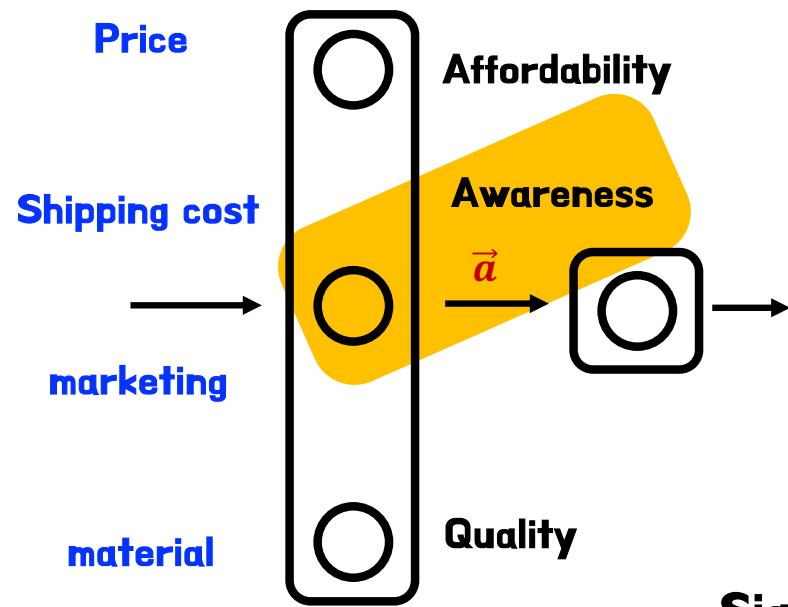


Implanting a 3<sup>rd</sup> eye

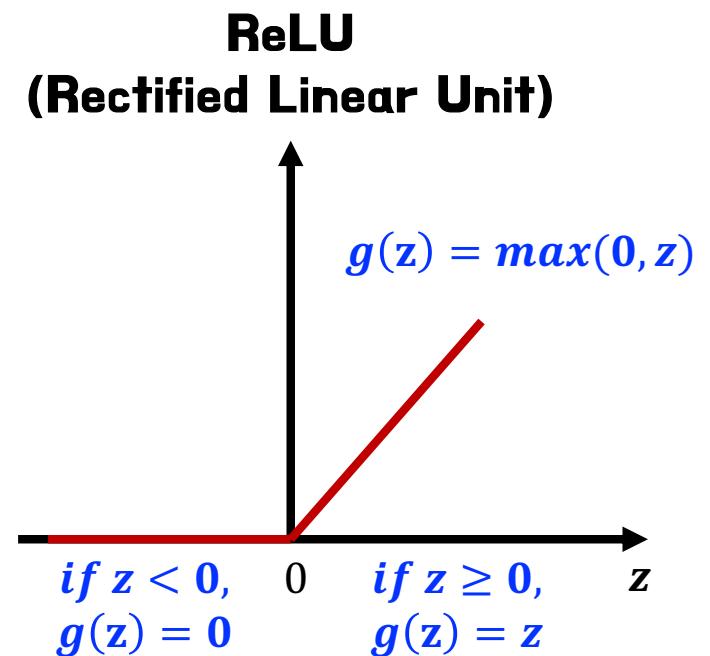
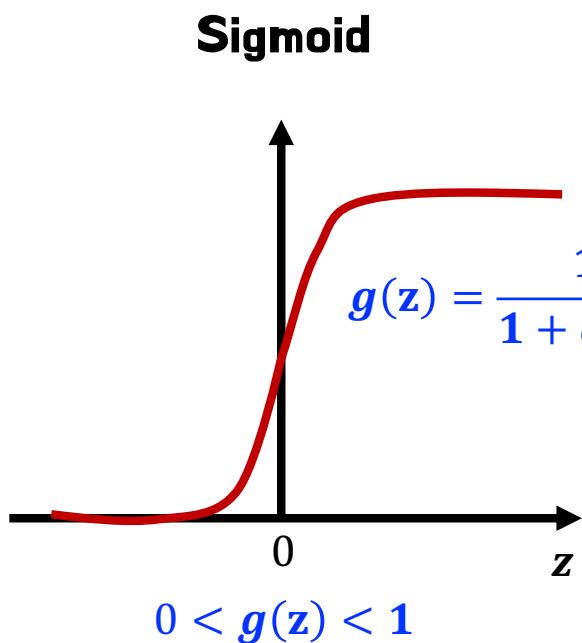
# **Activation function**



# Demand prediction example



$$a_2^{[1]} = g(\vec{w}_2^{[1]} \cdot \vec{x} + b_2^{[1]})$$

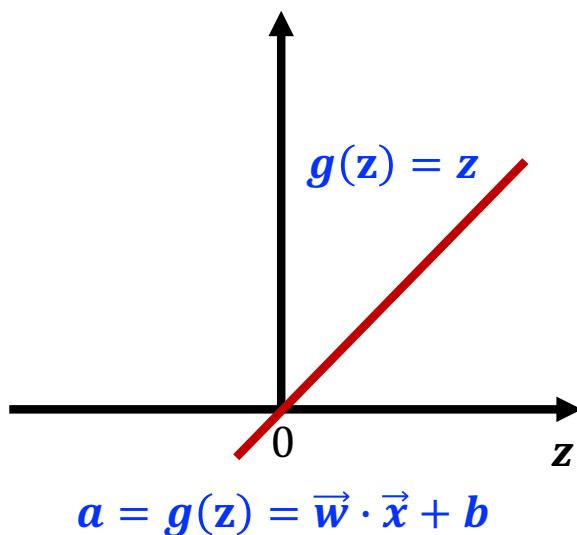


# Examples of activation functions

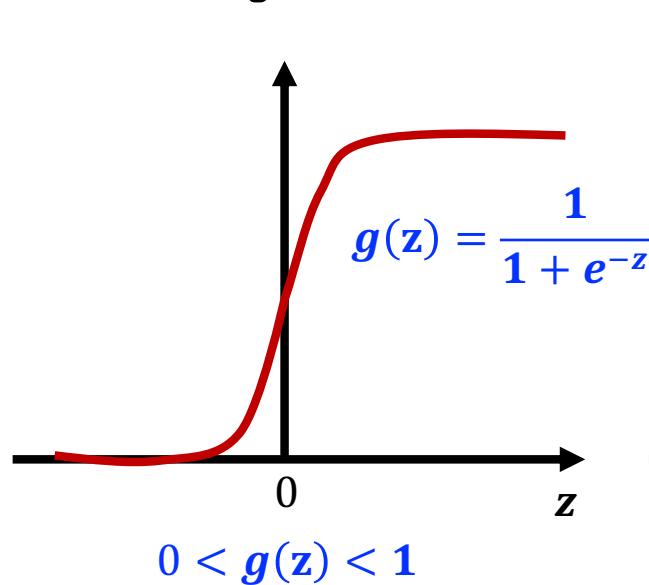
$$a_2^{[1]} = g(\vec{w}_2^{[1]} \cdot \vec{x} + b_2^{[1]})$$

“No activation function”

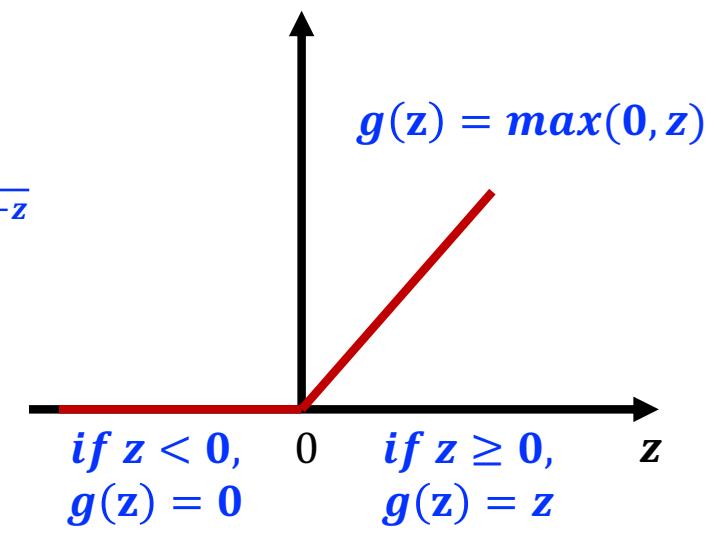
Linear activation  
function



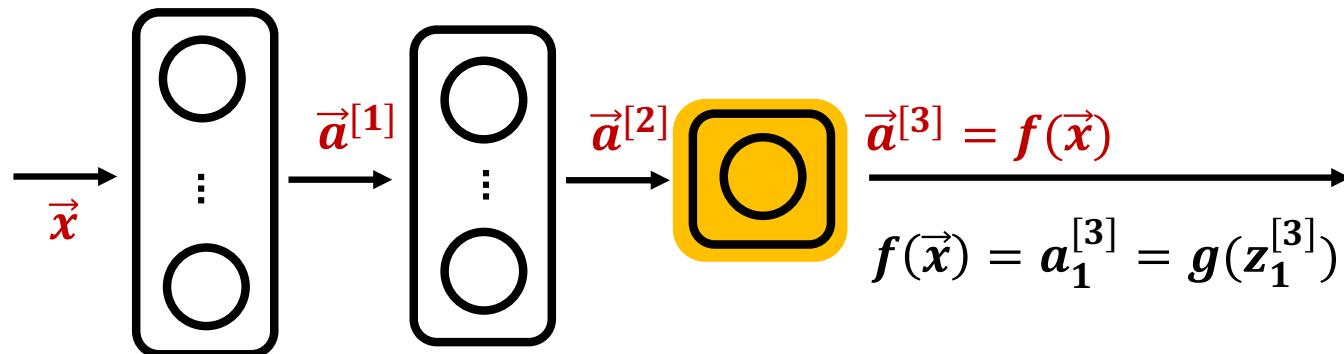
Sigmoid



ReLU  
(Rectified Linear Unit)



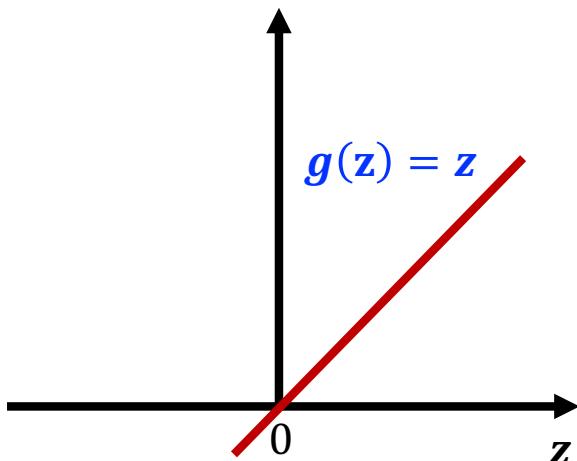
# Output layer



Choosing  $g(z)$  for output layer ?

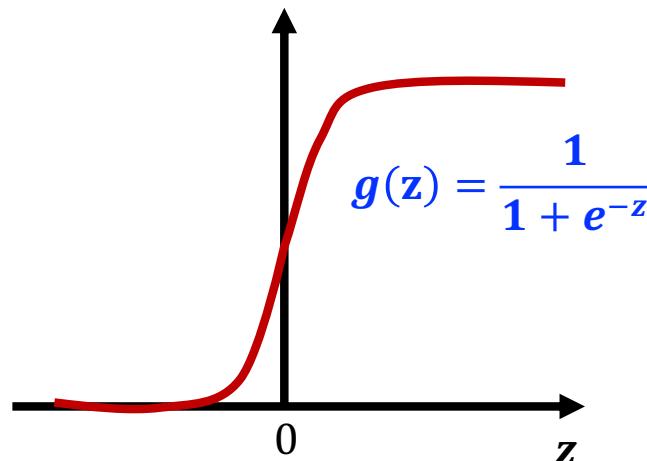
## Regression

Linear activation function  
 $y = +/-$



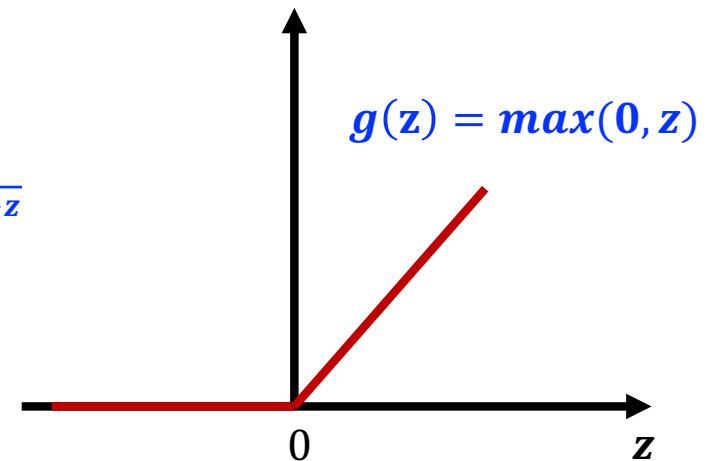
## Binary classification

Sigmoid  
 $y = 0/1$

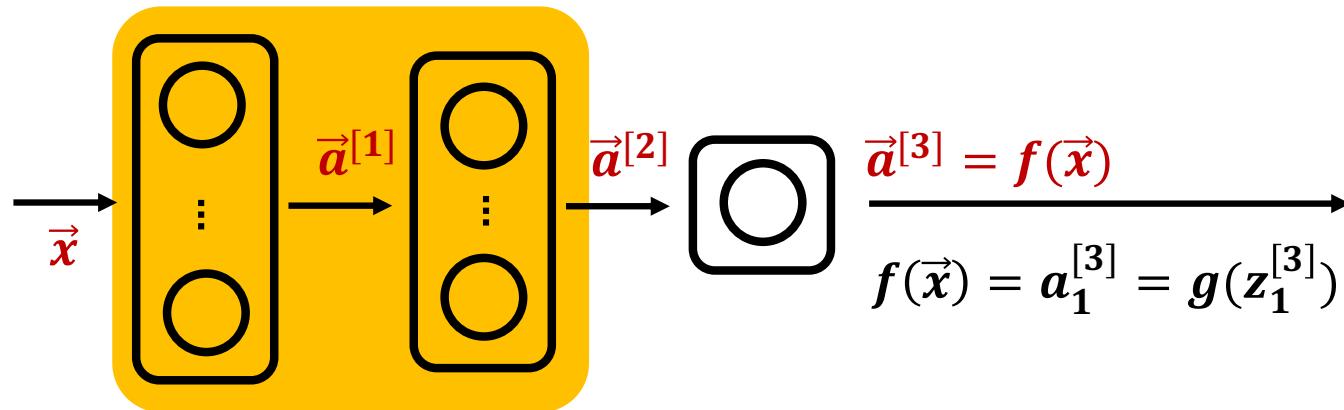


## Regression

ReLU  
 $y = 0 \text{ or } +$

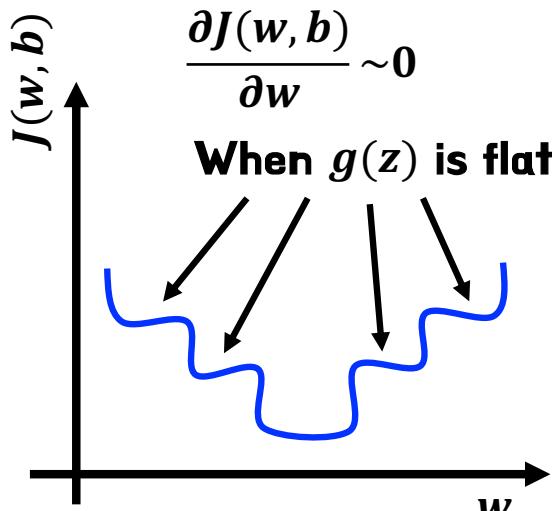
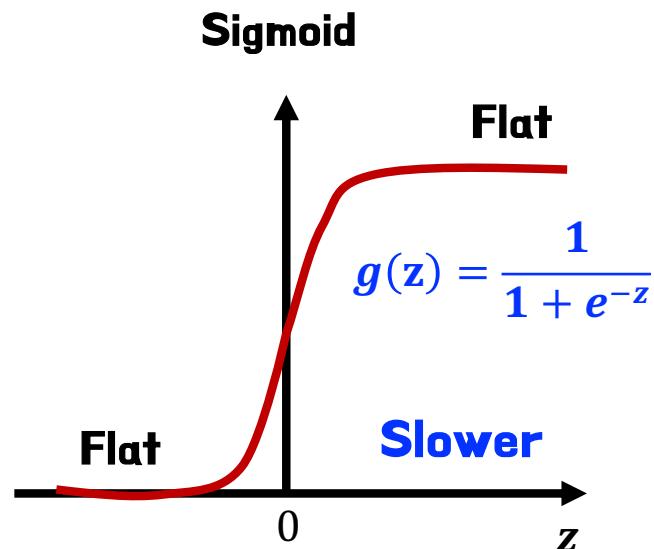


# Hidden layer

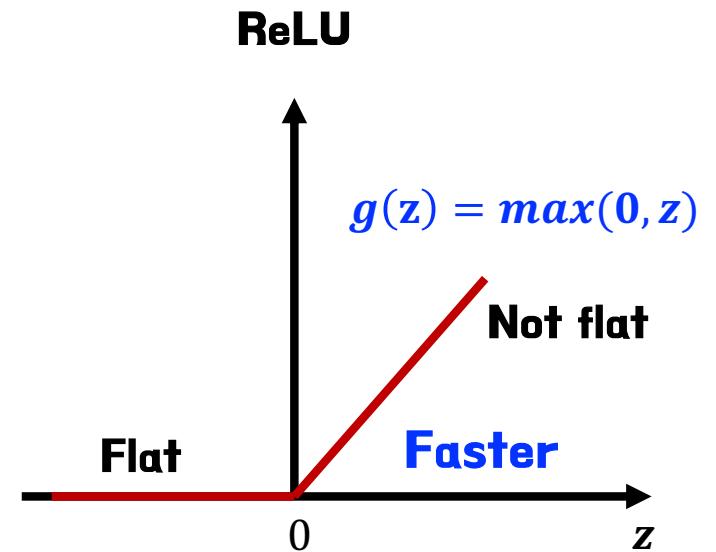


Choosing  $g(z)$  for hidden layer ?

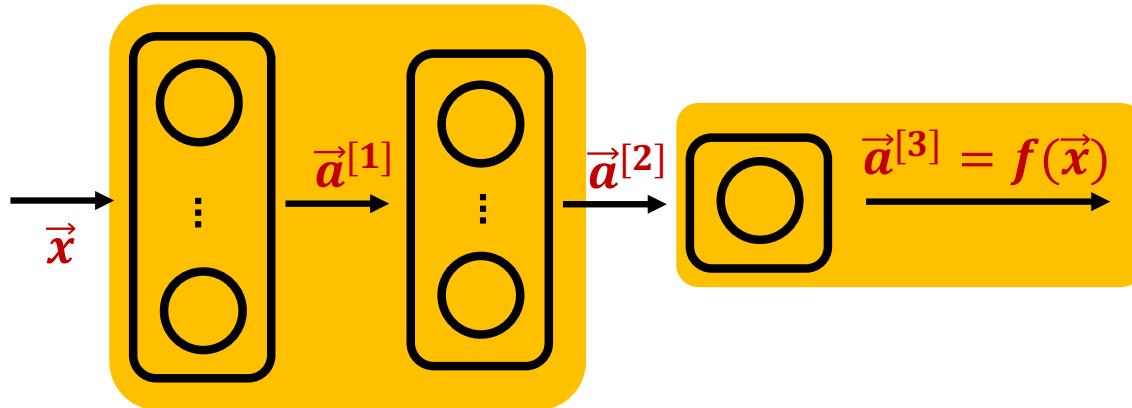
## Classical



## Most common



# Choosing activation summary



**ReLU** for hidden layers

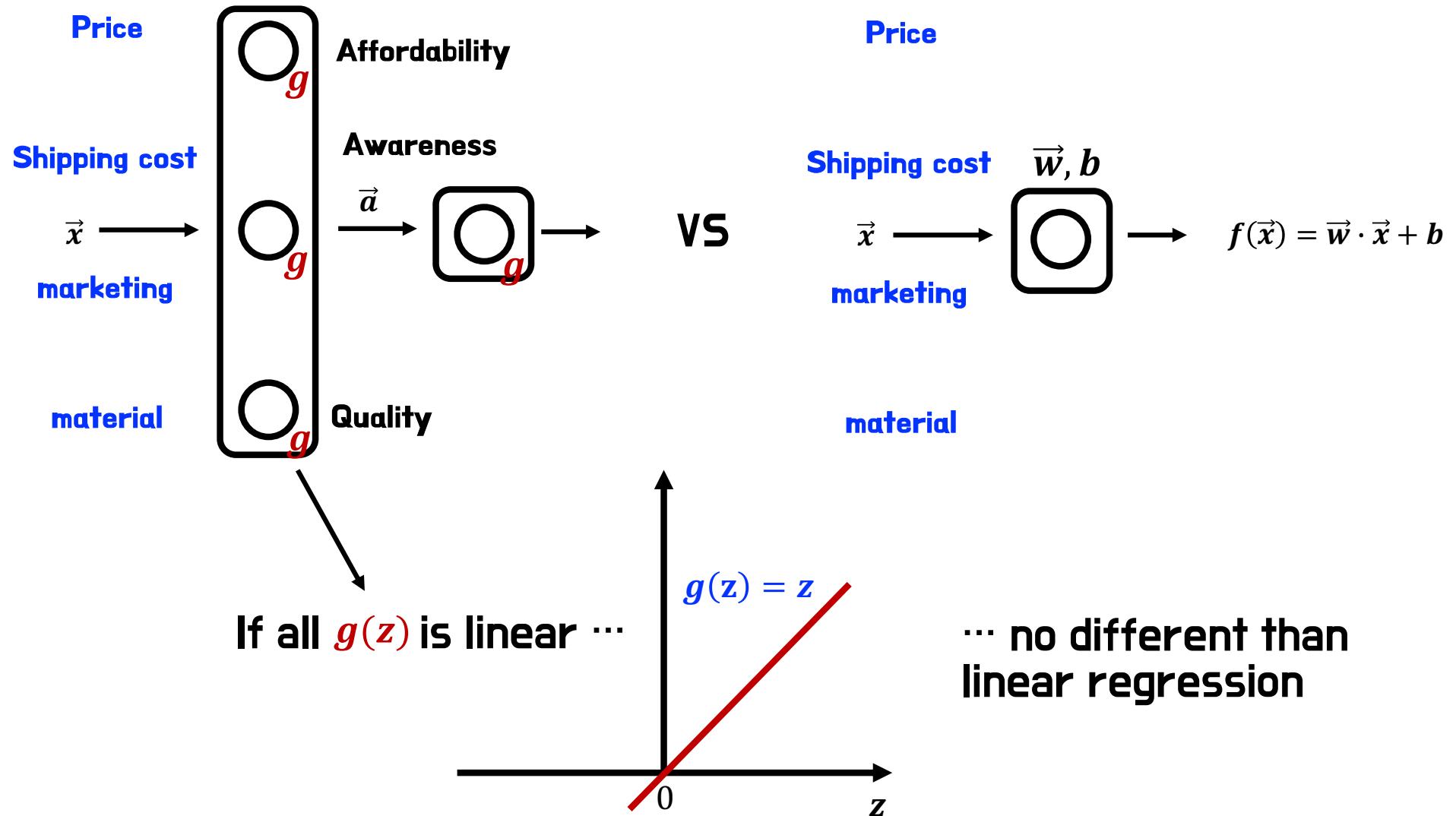
## Typical coding

```
from tf.keras.layers import Dense  
model = Sequential([  
    Dense(units=25, activation='relu'),  
    Dense(units=15, activation='relu'),  
    Dense(units=1, activation='sigmoid'),  
])
```

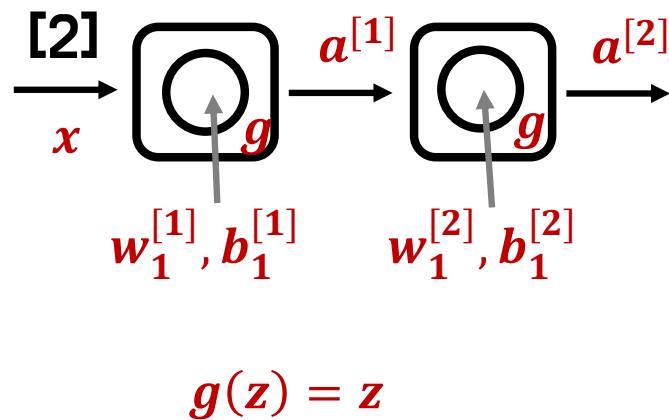
layer1  
layer2  
layer3 = output layer

There are another activation functions: 'Reacky ReLU', 'Tanh', 'Softmax'

# Why do we need activation functions ?



# Linear example



$$a^{[1]} = w_1^{[1]}x + b_1^{[1]}$$

$$a^{[2]} = w_1^{[2]}a^{[1]} + b_1^{[2]}$$

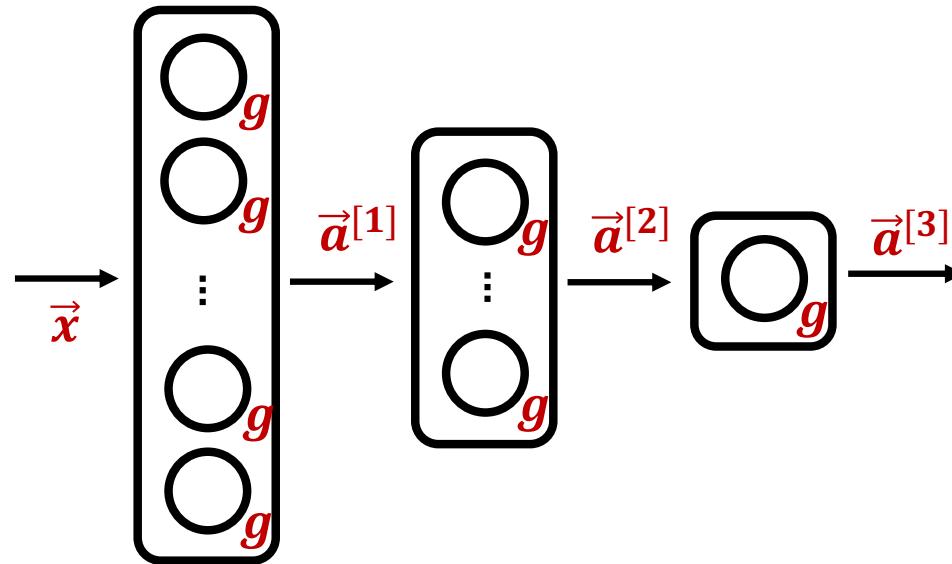
$$= w_1^{[2]}(w_1^{[1]}x + b_1^{[1]}) + b_1^{[2]}$$

$$= \underbrace{w_1^{[2]}w_1^{[1]}}_w x + \underbrace{(w_1^{[2]}b_1^{[1]} + b_1^{[2]})}_b$$

$$a^{[2]} = \mathbf{w}\mathbf{x} + \mathbf{b}$$

Again, same linear regression

# Example



$$g(z) = z$$

$$\vec{a}^{[3]} = \vec{w}_1^{[3]} \cdot \vec{a}^{[2]} + b_1^{[3]}$$

All linear (including output)  
→ Equivalent to linear regression

$$g(z) = \frac{1}{1 + e^{-z}}$$

$$\vec{a}^{[3]} = \frac{1}{1 + e^{-(\vec{w}_1^{[3]}\cdot \vec{a}^{[2]} + b_1^{[3]})}}$$

Output : sigmoid (hidden : all linear)  
→ Equivalent to logistic regression

**Don't use linear activation in hidden layers (use ReLU)**